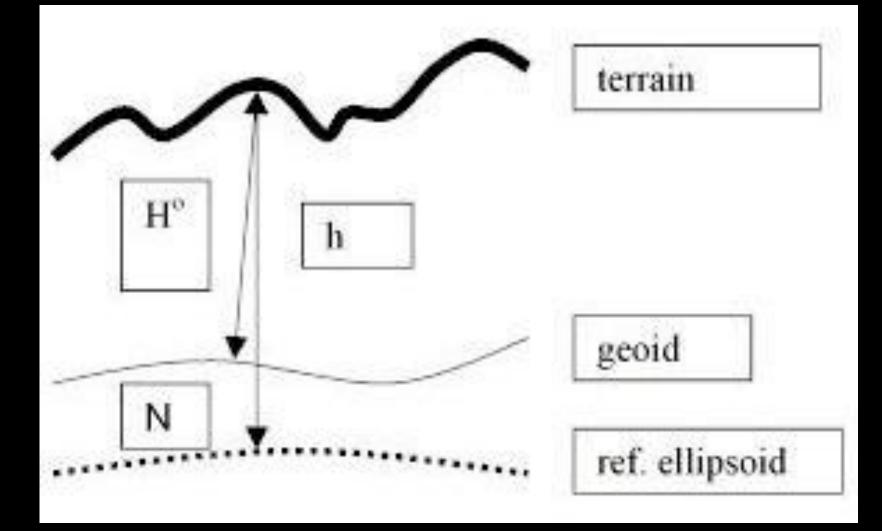
Gravity An Essential Layer in Defence GIS

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MOBITERRA

SOLUTIONS (INDIA) PRIVATE LIMITED



Bhaskaracharya 5th Century CE in his Surya Siddhanta

"Objects fall on the earth due to a force of attraction by the earth. Therefore, the earth, planets, constellations, moon and sun are held in orbit due to this attraction."

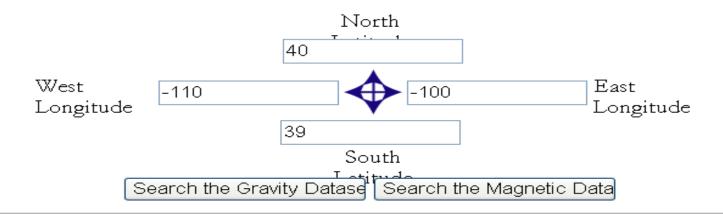
Presentation Scope

- Role of Gravity in Defence Applications
- International Developments
- Indian Gravity
- Mobiterra's Investment
 - Trajectory Algorithm
 - Deriving & validating Gravity Maps
 - Plumb line
 - Comparing Gravity Models

International Efforts

- CHAMP
- GRACE
- GOCE

• Satellite only & Combined Gravity Models



Search Results

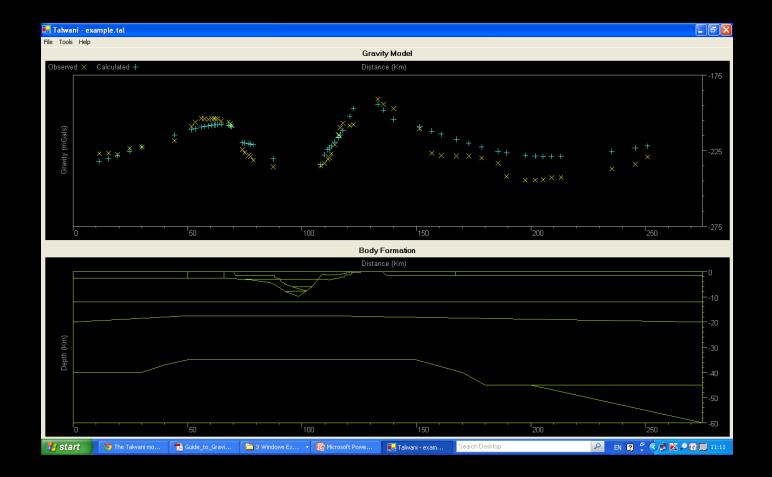
Number of Records found: 20043

					~
27	LonNAD83	Elevngvd29m	Elevngvd88m	ObsGrvLess9	7
	100 500005	1275 00	1075 50	2640.00	-
998300	-102.5003025	1375.00	1375.58	3649.90	
950000	-101.3954399	0963.50	0963.89	3758.80	-
000000	-101.4004400	0963.50	0963.89	3758.90	-
341700	-105.6347289	2649.30	2650.78	3292.36	
713300	-105.7718930	2696.40	2697.92	3287.78	
250000	-107.5256114	2108.90	2110.45	3383.90	
248300	-107.5254414	2108.90	2110.45	3383.90	
930000	-105.5935577	2644.70	2646.16	3291.14	
975000	-105.5980578	2648.20	2649.66	3288.16	~
<				>	1

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http://irpsrvgis00.utep.edu/repositorywebsite/Default.aspx

Interpreting Gravity Anomaly



Talwani

Indian Gravity

- G&RB, NGRI, WIHG,..
- 3500 GT Points, 17000 BMs,
 35000 Gravity Stations

Source: Availability and Accessibility of Geodetic and Map data in India, M. N. Kulkarni

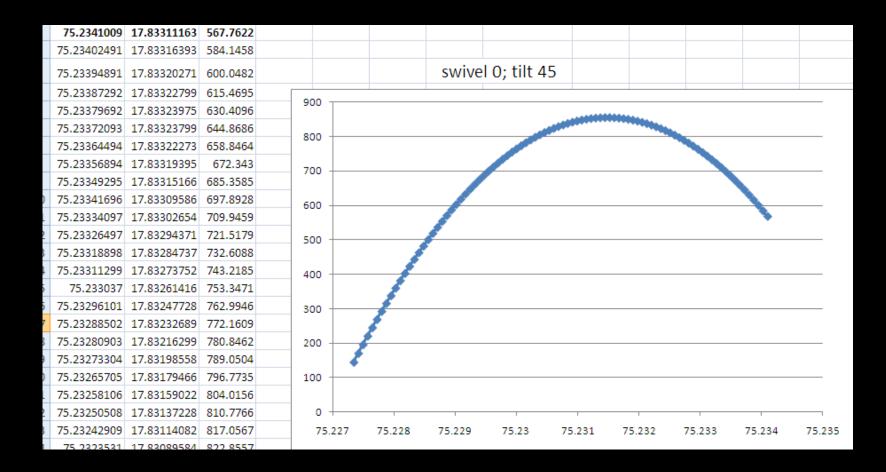
<u>Impact of Gravity Anomalies on</u> <u>Ballistic Trajectories</u>

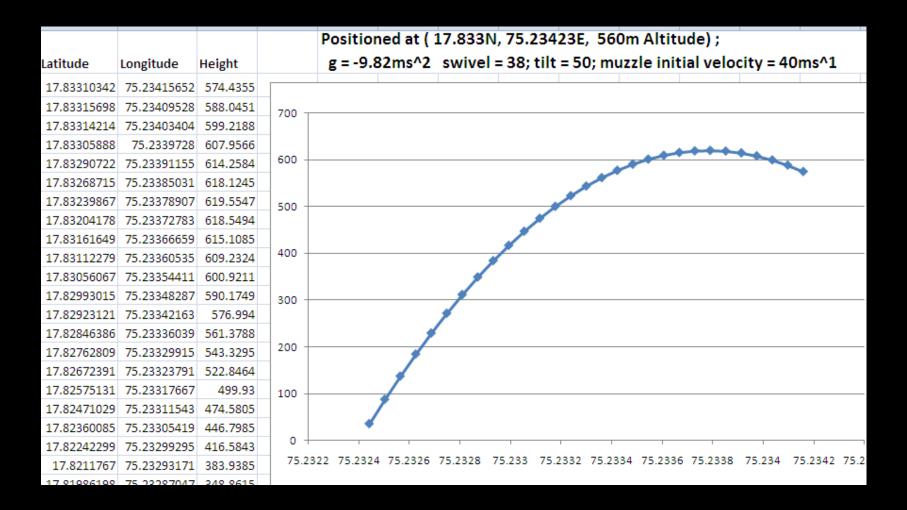
- On height, range, time-of-flight of Ballistic Trajectory
 Modifying the equations of motion with gravity anomaly
- On launch velocity
 - from the range if the angle of launch is known.
 - if the maximum height and range are known,
- On angle-of-launch
 - Affects the range.
 - If the launch velocity is known, the required angle of launch for a desired range can be calculated from the motion equations.

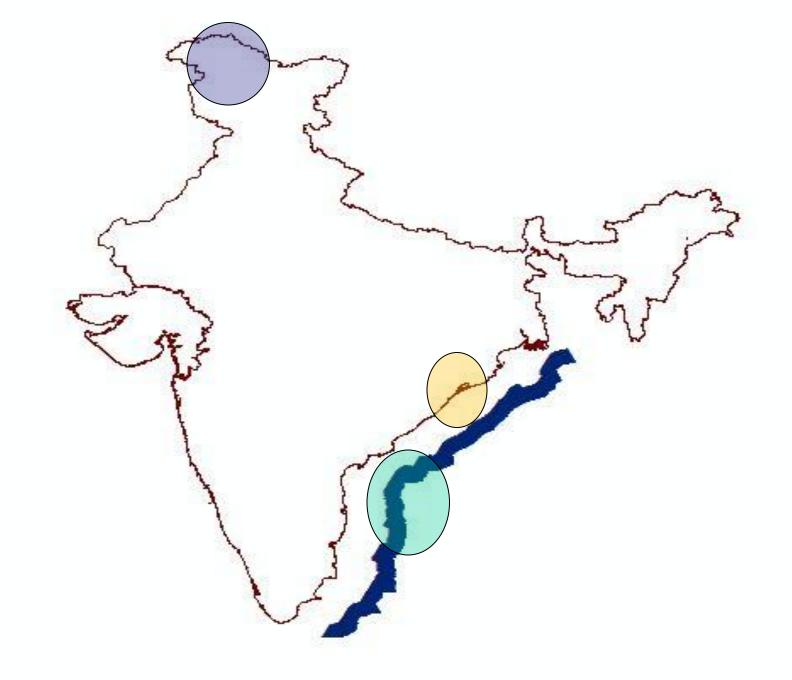
Trajectory – Variables

Various values of Canon-length, muzzle-velocity, swing, tilt Gravity: Constant and varying

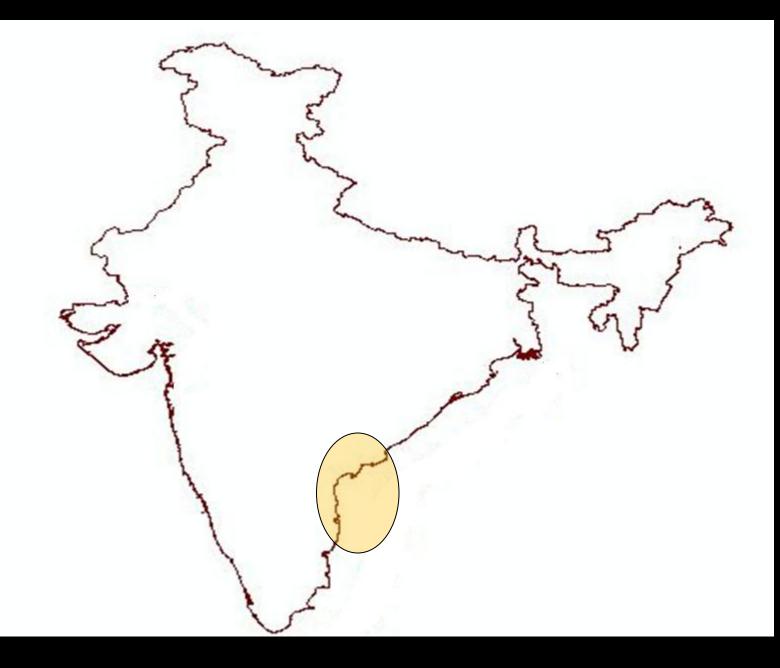
case	input	check	Non-zero variables
1	tilt = 90	Vertical trajectory expected	All other than tilt, (constant g)
1g	Case 1 with varying gravity	No deviations from Case 1 trajectory	
2	swing=90; tilt=0;	horizontal trajectory expected	Muzzle-velocity, canon constant g)
2σ	Case 2 with varying	By-and-large horizontal, but with	
2g	gravity	fluctuations expected	
3	Muzzle velocity=0	Only one epoch expected	All other than muzzle (constant g)
3g	Case 3 with varying gravity	Same as Case 3	
4	Canon- length=0;swing=90;tilt= 0	The first epoch and the input position matches. This also checks the <i>geodetic</i> \rightarrow <i>ECEF</i> \rightarrow <i>geodetic</i> transformation.	Muzzle-velocity (constant g)
4g	Case 4 with varying gravity	Same as case 4	



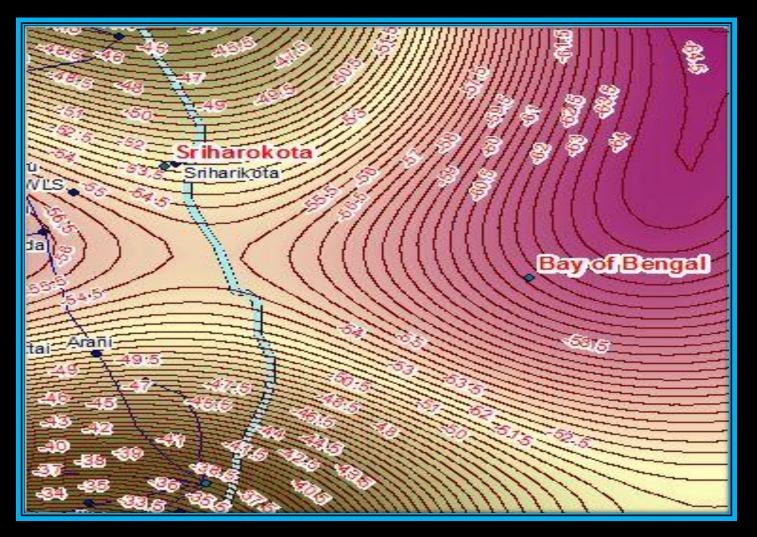




Gravity = f(X, Y, Z, t)

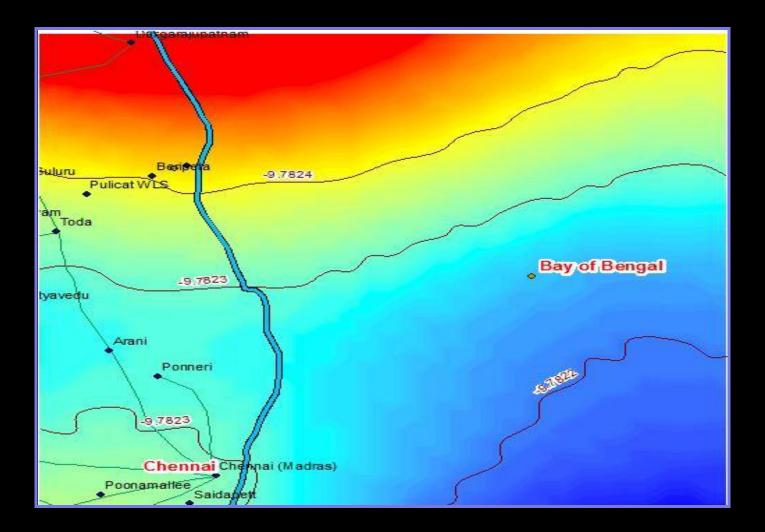


Gravity Anomaly Contour Interval = 0.5 mGal Range: - 65 to -32 mGal

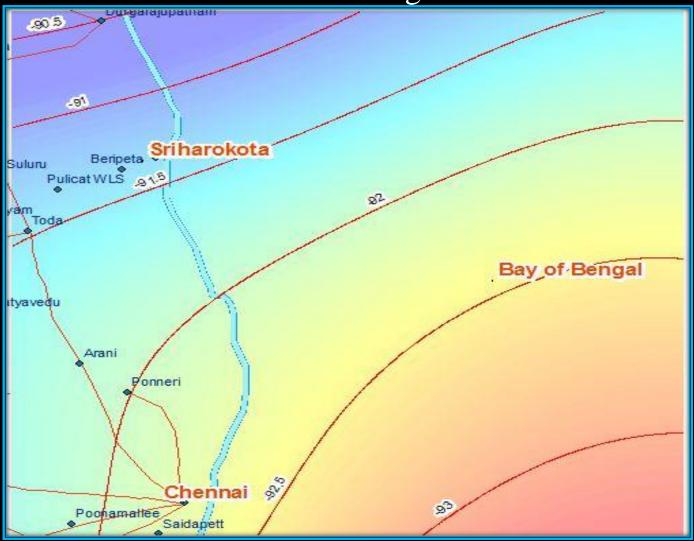


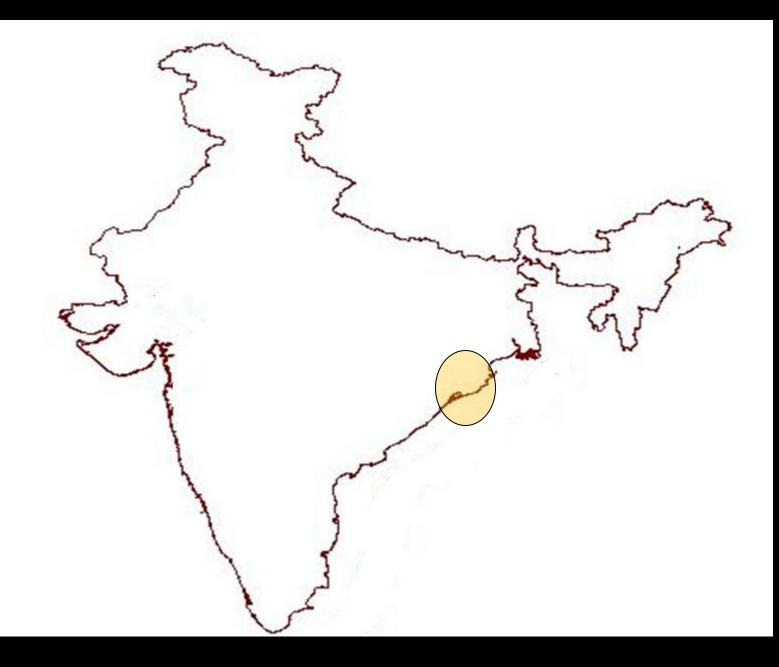
Acceleration Due to Gravity

Contour Interval = 0.0001 m/sec² Range -9.78264 to -9.78214 m/sec²



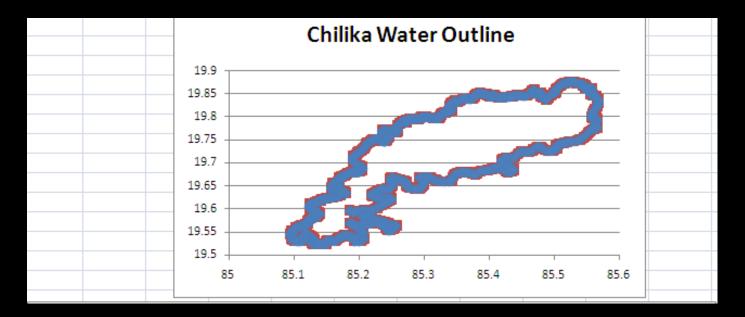
Geoid Height Contour Interval = 0.5m Range: -90.329 to -93.369m

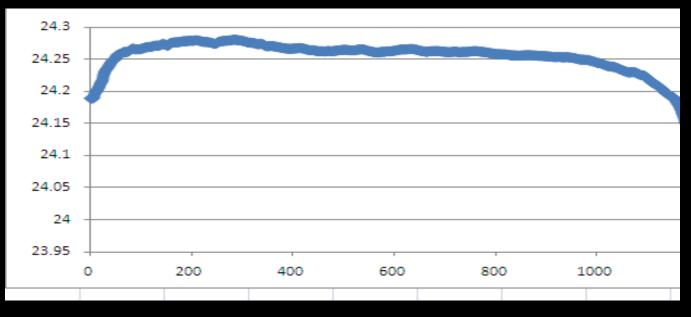


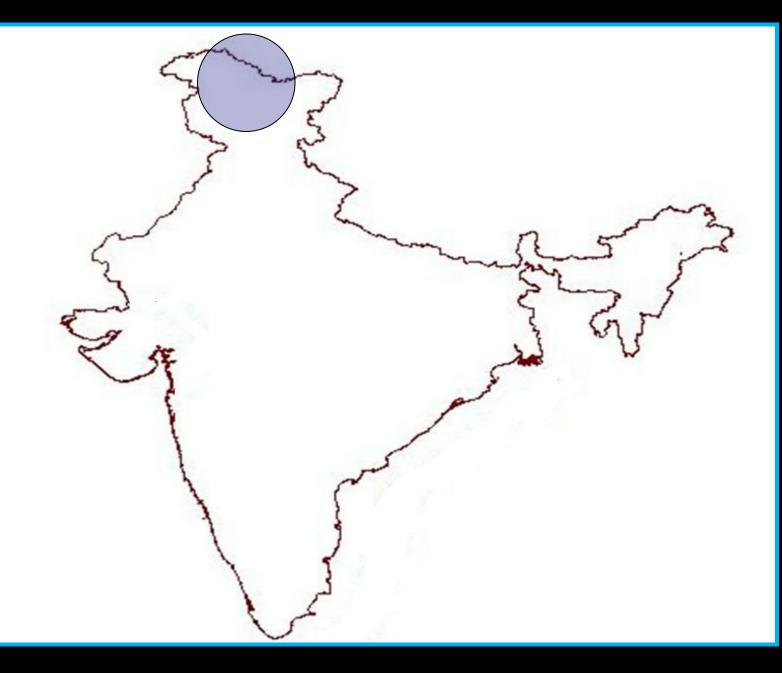


Shoreline Condition Chilika lake: 60km x 20km

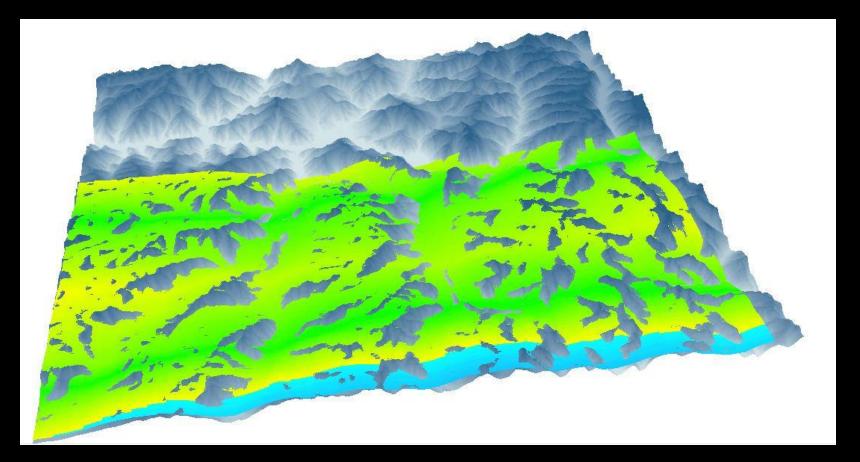








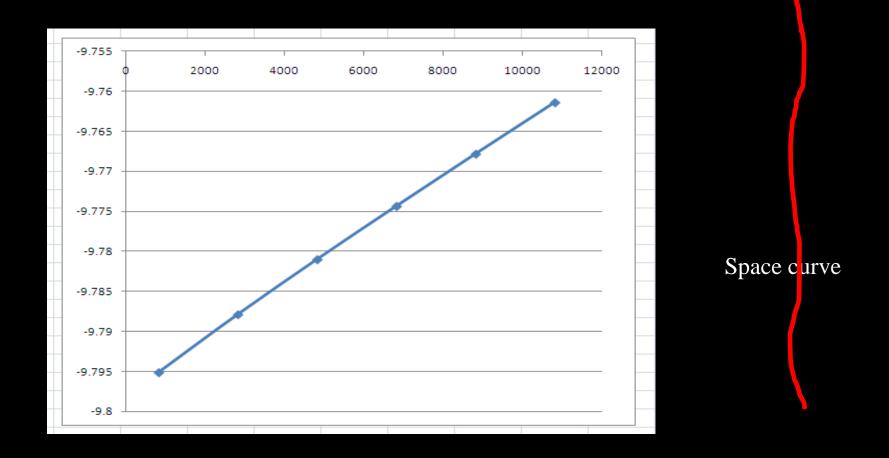
Gravity Anomaly Map of Kargil Environs overlaid on the Terrain Model



Comparing 96 & 2008 Gravity Models

	Evere	st with Va	rying Z	Mod	lel2008 Gx,G	y, Gz	Mode	el 96 Gx, G	y, Gz	delta Gx	delta Gy	delta Gz	N-96	N-08	
2	7d59'17N	86d55'328	820	0.0001	0.00134	-9.79513	-0.00038	0.00087	-9.79151	0.00124	0.00047	-0.00362			
- 2	7d59'17N	86d55'328	2820	0.00009	0.00122	-9.78788	-0.00033	0.00086	-9.78525	0.00113	0.00036	-0.00263			
2	7d59'17N	86d55'328	4820	0.00006	0.00114	-9.781	-0.00029	0.00086	-9.779	0.00108	0.00028	-0.002			
2	7d59'17N	86d55'328	6820	0.00002	0.00108	-9.77435	-0.00025	0.00085	-9.77276	0.00106	0.00023	-0.00159	-28.7437	-28.4947	
2	7d59'17N	86d55'328	8820	-0.00001	0.00103	-9.76782	-0.00021	0.00084	-9.76653	0.00104	0.00019	-0.00129			
2	7d59'17N	86d55'328	10820	-0.00003	0.001	-9.76139	-0.00018	0.00083	-9.76031	0.00103	0.00017	-0.00108			
2	7d59'17N	86d55'328	20820	-0.00004	0.00088	-9.72983	-0.00004	0.00076	-9.72934	0.00092	0.00012	-0.00049			
D															
1					Average Gz	-9.77106			-9.77106						
2					StanDev Gz	0.046174			0.046174						
4 5	0 <u></u>														
7 3	-0	.001	820	2820	4820	6820	883	20	10820	20820					
ə D															
1	-0.	.002													
2	-0	Delta Gz: For Varying heights of the projectile at a point													
4			X-axis: Projectile Z in metres												
5	-0	Y-axis: Gravity change between Models of 96 and '08 in m/s^2													

Altitude Vs Acceleration of Gravity



In Conclusion

- Indian Defence Systems are *into* GIS.
- Gravity needs to be part of D-GIS

 Improved positioning & deployment
 Discreet use of weaponry
- Gravity forms part of core GeoInt

Discussion

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